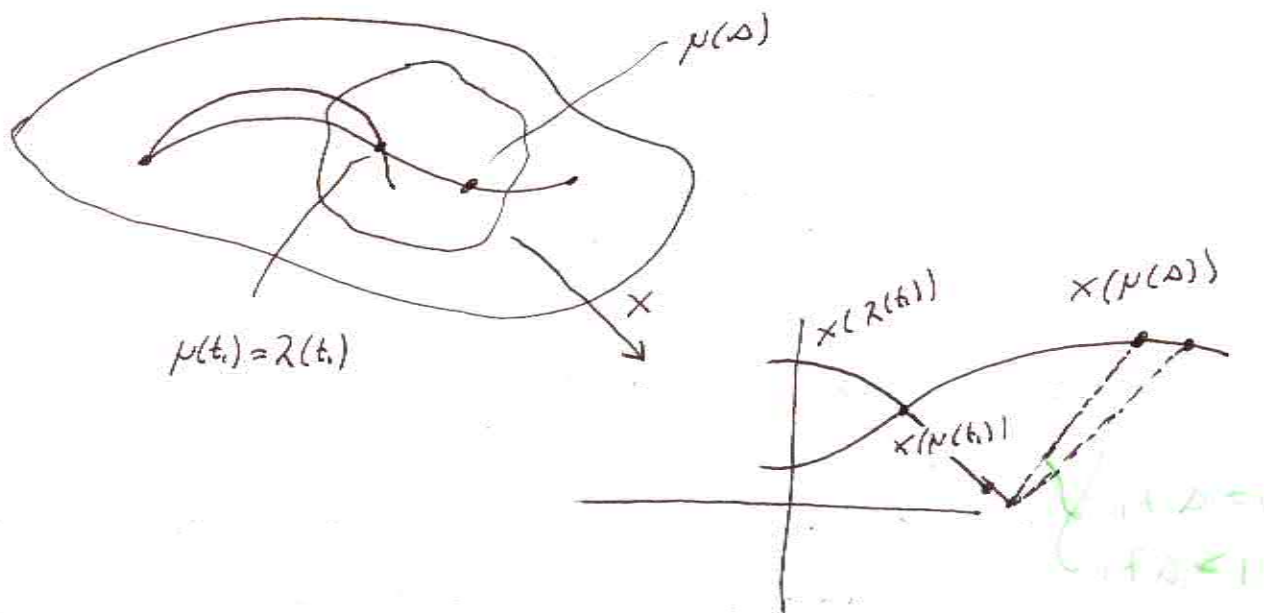
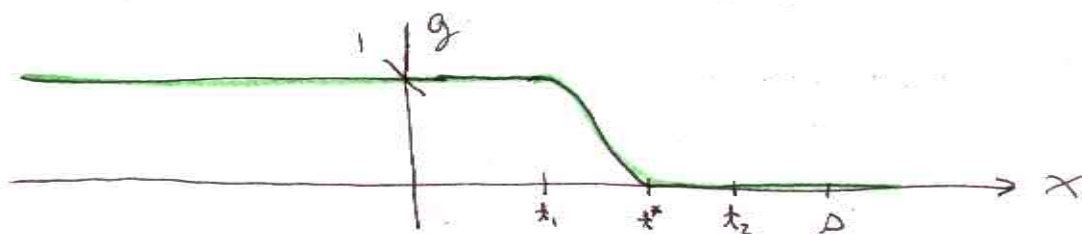


Now consider the function  $x \circ \gamma$



Choose  $t^*, t_2 \geq t_1 < t^* < t_2 < t_1 + \delta < \Delta$

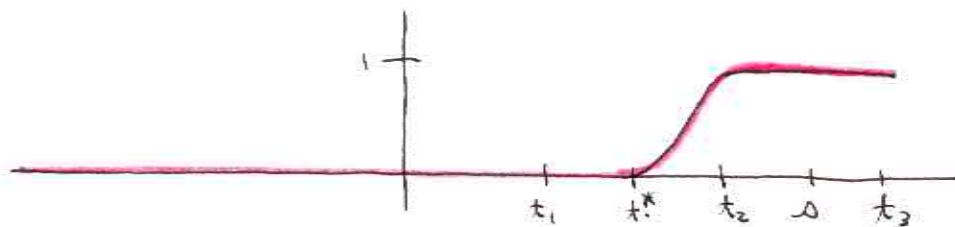
Define  $g: \mathbb{R} \rightarrow \mathbb{R}$



Then  $g(t)x(\gamma(t))$  is smooth for  $(t_1 - \delta, \infty)$  with value zero for  $t \geq t^*$

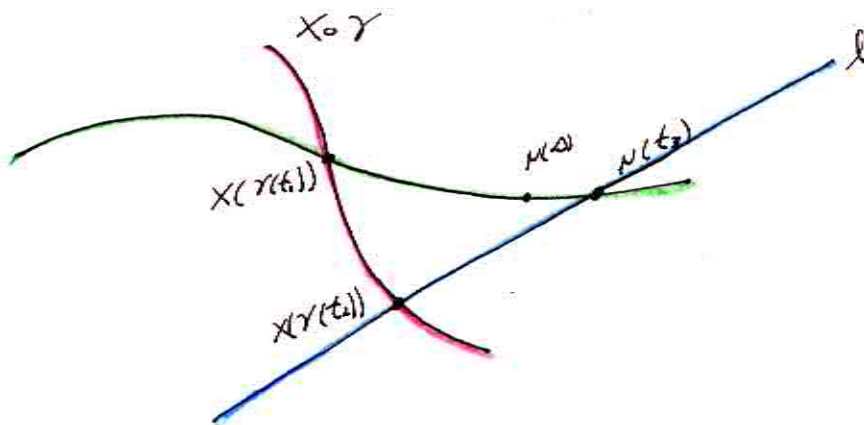
If  $\Delta = 1$  then we define  $t_3 = \Delta$ . If  $\Delta < 1$  let  $\Delta < t_3 < 1$ . We show

$\exists$  smooth  $\tilde{\gamma}: [0, t_3] \rightarrow M$  such that  $\tilde{\gamma}(0) = \mu(0)$ ,  $\tilde{\gamma}(t_3) = \mu(t_3)$  which will imply that  $t_3 \in V$  and  $t_3 > \Delta = \text{lub}(V)$ . We define  $h: \mathbb{R} \rightarrow$



Define  $l: \mathbb{R} \rightarrow \mathbb{R}^n$  to be a ~~straight~~ smooth function whose graph is a straight line in  $\mathbb{R}^m$  such that  $l(t_2) = x(\gamma(t_2))$  and  $l(t_3) = x(\mu(t_3))$

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 $\mathbb{R}^n$ 

$h(t)l(t)$  is defined on all of  $\mathbb{R}$ . Let  $\psi(t) = g(t)x(r(t)) + h(t)l(t)$  for all  $t > t_1 - \delta$ . Now note the properties of  $\psi$

$$\begin{aligned} \text{Claim: } \Rightarrow \psi|_{(t_1 - \delta, t_1]} &= (x \circ \gamma)|_{(t_1 - \delta, t_1]} \\ \psi|_{[t_1, t^*]} &= g(t)x(r(t)) \\ \psi|_{[t^*, t_2]} &= h(t)l(t) \\ \psi|_{[t_2, \infty)} &= l(t) \end{aligned} \left. \vphantom{\begin{aligned} \text{Claim: } \Rightarrow \psi|_{(t_1 - \delta, t_1]} \\ \psi|_{[t_1, t^*]} \\ \psi|_{[t^*, t_2]} \\ \psi|_{[t_2, \infty)} \end{aligned}} \right\} \begin{array}{l} \text{from} \\ \text{defining} \\ \text{graphs of} \\ \text{functions} \end{array}$$

Now  $x^{-1} \circ \psi$  is smooth in  $(t_1 - \delta, t_3]$  and agrees with  $\gamma$  on  $(t_1 - \delta, t_3]$ . Finally, we can define  $\tilde{\gamma}$

$$\tilde{\gamma}(t) = \begin{cases} \gamma(t) & 0 \leq t \leq t_1 \\ x^{-1}(\psi(t)) & t_1 \leq t \leq t_3 \end{cases}$$

Now  $\tilde{\gamma}: [0, t_3] \rightarrow M$  smooth,  $\tilde{\gamma}(0) = \gamma(0) = \mu(0)$

$$\tilde{\gamma}(t_3) = x^{-1}(\psi(t_3)) = x^{-1}(h(t_3)l(t_3))x(r(t_2)) = x^{-1}(x(\mu(t_2))) = \mu(t_2)$$

$$\Rightarrow t_3 \in V \text{ and } t_3 > \text{lub}(V) \longrightarrow \longleftarrow$$

QED

$$\mathcal{F}^\infty(p) = C_p^\infty(M)$$

If  $M$  is a manifold, we say that  $f \in C_p^\infty(M)$  iff  $f$  is a smooth function from an open subset  $U$  of  $M$  into  $\mathbb{R}$  such that  $p \in U$

Now let  $f, g \in C_p^\infty(M)$  then

$$(f+g)(x) = f(x) + g(x)$$

$$(cf)(x) = cf(x)$$

$$(fg)(x) = f(x)g(x)$$

If  $f$  is defined on  $U$  and  $g$  is defined on  $V$  then  $\text{dom}(f+g) = U \cap V$  and  $\text{dom}(cf) = \text{dom}(f)$  etc...

$$\hat{0}(x) = 0$$

$$f + \hat{0} = f = \hat{0} + f$$

$$f + (-1)f = \hat{0}|_U \neq \hat{0} \quad \text{domains a problem}$$

problem 1.6.2  
Extra if  
we do well

We say that  $X$  is a first order linear differential operator at  $p \in M$  iff

$$X : C_p^\infty(M) \longrightarrow \mathbb{R} \text{ such that}$$

$$1) X(f+g) = X(f) + X(g)$$

$$2) X(cf) = cX(f)$$

$$3) X(fg) = f(p)X(g) + g(p)X(f)$$

(Another view of Tangent  
vectors)

Let  $(U, x)$  be a chart on  $M$ . We Define the following

$$\frac{\partial}{\partial x^i} \Big|_p \equiv \frac{\partial}{\partial x^i} (p) \quad (\text{notation})$$

$$\frac{\partial}{\partial x^i} (p) (f) \equiv \frac{\partial (f \circ x^{-1})}{\partial u^i} (x(p))$$

which the  $(u^1, u^2, \dots, u^m) \in \mathbb{R}^m$  and  $x(U) \stackrel{\text{open}}{\subseteq} \mathbb{R}^m$

Notice that  $\frac{\partial f}{\partial x^i} (p)$  has no particular meaning on its own.

### Properties

$$(f+g) \circ x^{-1} = f \circ x^{-1} + g \circ x^{-1}$$

$$(fg) \circ x^{-1} = (f \circ x^{-1})(g \circ x^{-1})$$

$$(cf) \circ x^{-1} = c(f \circ x^{-1})$$

$$\frac{\partial}{\partial x^i} \Big|_p (f+g) = \frac{\partial}{\partial x^i} \Big|_p (f) + \frac{\partial}{\partial x^i} \Big|_p (g)$$

## Root Length $L$

$$1.2.6 \quad (u_1, u_2, u_3, u_4, u_5, u_6) \in \mathbb{R}^6$$

$$L(a_1, a_2, a_3)$$

Show manifold same as  $\mathbb{R}^3 \times S^2$

So he wants a mapping  $\varphi: \mathbb{R}^3 \times S^2 \rightarrow \mathbb{R}^6$

Show  $\varphi$  a 1-1 mapping. We set up a 1-1 correspondence between configuration space and manifold

I. TEST - 2 weeks from  
2/15/2001

II. Homework Next Thursday

1.7.1

1.7.2

1.8.3

1.8.4

1.2.4

EASY:  $\mathbb{R}^3 \times S^2 \times (L_1, L_2)$

## Projective Plane Problems

$$\mathbb{R}P^2 = \{[P, -P] \mid P \in S^2\}$$

$$P \in S^2 \iff x(P)^2 + y(P)^2 + z(P)^2 = 1$$

$$\mathbb{R}P^2 = \left\{ \left\{ (x, y, z), (-x, -y, -z) \right\} \mid x^2 + y^2 + z^2 = 1 \right\}$$

$$M_1([P, -P]) = \left( \frac{y}{z}, \frac{z}{x} \right) = M_1(\{(x, y, z), (-x, -y, -z)\})$$

$$x^2 + y^2 + z^2 = 1$$

$F: S^2 \rightarrow \mathbb{R}P^2$   $\chi$  a chart on  $S^2$

$$\begin{array}{ccc} \chi \downarrow & & \downarrow M_1 \end{array}$$

$$\xrightarrow{\chi^{-1} \circ F \circ M_1} \text{(smooth?)}$$



$$C_p^\infty(M) = \tilde{f}^\infty(P) : \text{Book's Notation}$$

$$\Sigma_p : C_p^\infty M \longrightarrow \mathbb{R}$$

$$\Sigma_p (c_1 f_1 + c_2 f_2) = c_1 \Sigma_p (f_1) + c_2 \Sigma_p (f_2)$$

$$\Sigma_p (fg) = f(P) \Sigma_p (g) + g(P) \Sigma_p (f)$$

Notation

$$\left. \frac{\partial}{\partial x^i} \right|_p = \frac{\partial}{\partial x^i}(P) = \partial_i^x$$

$$\frac{\partial}{\partial u^i} = \partial_i$$

Differentiation with respect to  $x^i$  from chart

$$\text{Def: } \left. \frac{\partial}{\partial x^i}(P)(f) \equiv \frac{\partial (f \circ x^{-1})}{\partial u^i}(x(P)) = \partial_i (f \circ x^{-1})(x(P)) \right.$$

$$(fg) \circ x^{-1} = (f \circ x^{-1})(g \circ x^{-1})$$

$$\frac{\partial}{\partial x^i}(P)(fg) = \frac{\partial (fg \circ x^{-1})}{\partial u^i}(x(P)) = \frac{\partial}{\partial u^i} \left( (f \circ x^{-1})(g \circ x^{-1}) \right) (x(P))$$

$$= (f \circ x^{-1})(x(P)) \frac{\partial}{\partial u^i} (g \circ x^{-1})(x(P)) + (g \circ x^{-1})(x(P)) \frac{\partial}{\partial u^i} (f \circ x^{-1})(x(P))$$

$$= f(P) \frac{\partial}{\partial x^i}(P) g + g(P) \frac{\partial}{\partial x^i}(P) f$$