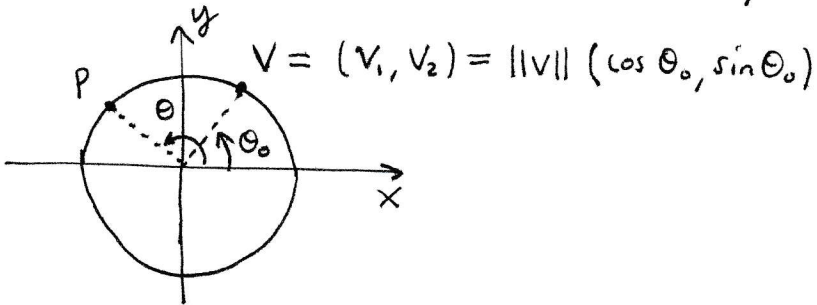


P69 Let $G = O(2, \mathbb{R}) = \{R \in \mathbb{R}^{2 \times 2} \mid R^T R = I\}$ act on \mathbb{R}^2 via matrix multiplication; $R * v = Rv \quad \forall v \in \mathbb{R}^2, R \in G$. Calculate $\mathcal{O}(v)$ for each $v \in \mathbb{R}^2$ and G_v for each $v \in \mathbb{R}^2$

The orbit of $v = 0$ is easy to calculate as $R(0) = 0$ for all $R \in G \therefore \mathcal{O}(0) = \{0\}$. Suppose $v \neq 0$ consider $R * v = Rv$ has $\|Rv\|^2 = (Rv) \cdot (Rv) = (Rv)^T Rv$ hence $\|Rv\|^2 = v^T R^T R v = v^T I v = v^T v = \|v\|^2$. We find the points in the orbit of v are the same distance from the origin $(0,0)$ as is v . Thus $\mathcal{O}(v)$ is a subset of the circle $x^2 + y^2 = \|v\|^2$.

Polar coordinates give $r = \|v\|$ hence an arbitrary point on the circle is $(\|v\| \cos \theta, \|v\| \sin \theta) = P$



To obtain P in $\mathcal{O}(v)$ we consider the rotation by $\theta - \theta_0 = \beta$.

Let $R = \begin{bmatrix} \cos(\theta - \theta_0) & -\sin(\theta - \theta_0) \\ +\sin(\theta - \theta_0) & \cos(\theta - \theta_0) \end{bmatrix}$ you can check $R^T R = I \therefore R \in G$

and $R * v = \begin{bmatrix} \cos(\theta - \theta_0) & -\sin(\theta - \theta_0) \\ +\sin(\theta - \theta_0) & \cos(\theta - \theta_0) \end{bmatrix} \begin{bmatrix} \|v\| \cos \theta_0 \\ \|v\| \sin \theta_0 \end{bmatrix}$
 $= (\|v\| [\cos(\theta - \theta_0) \cos \theta_0 - \sin(\theta - \theta_0) \sin \theta_0], \|v\| [\sin(\theta - \theta_0) \cos \theta_0 + \cos(\theta - \theta_0) \sin \theta_0])$
 $= \|v\| (\cos(\theta - \theta_0 + \theta_0), \sin(\theta - \theta_0 + \theta_0))$
 $= \|v\| (\cos \theta, \sin \theta)$
 $= P \therefore \mathcal{O}(v) = \text{circle centered about } (0,0) \text{ through } v$

P69 continued

We've shown $O(0) = \{0\}$ and $O(v) = \{w \mid \|w\|^2 = \|v\|^2\}$ for $v \neq 0$.

Consider, $O(2, \mathbb{R})$ has normal subgroup $SO(2, \mathbb{R})$ where

$$SO(2, \mathbb{R}) = \text{Ker}(\det) = \{R \in O(2, \mathbb{R}) \mid \det(R) = 1\} = H$$

Furthermore, $O(2, \mathbb{R}) = H \cup \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} H$ as $\det \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = -1$.

Now, it can be shown $R \in SO(2, \mathbb{R})$ has form $R = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$
for some $\theta \in \mathbb{R}$. Hence $R \in \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} H$ has the form,

$$\begin{aligned} R &= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \\ &= \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix} \end{aligned}$$

So in total, $R \in O(2, \mathbb{R})$ has the form $R = \begin{bmatrix} \cos \theta & \sin \theta \\ \varepsilon \sin \theta & \varepsilon \cos \theta \end{bmatrix}$

where $\varepsilon = 1$ for $R \in SO(2, \mathbb{R})$ and $\varepsilon = -1$ for $R \in \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} SO(2, \mathbb{R})$.

Let $(x, y) \in \mathbb{R}^2$ be fixed point of $R = \begin{bmatrix} \cos \theta & \sin \theta \\ \varepsilon \sin \theta & \varepsilon \cos \theta \end{bmatrix}$,

$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\varepsilon \sin \theta & \varepsilon \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} \Rightarrow \begin{aligned} x \cos \theta + y \sin \theta &= x \\ -\varepsilon x \sin \theta + \varepsilon y \cos \theta &= y \end{aligned}$$

Here think of $\cos \theta, \sin \theta$ as the unknowns and write,

$$\begin{bmatrix} x & y \\ \varepsilon y & -\varepsilon x \end{bmatrix} \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} \quad (*)$$

This linear system has $\det \begin{bmatrix} x & y \\ \varepsilon y & -\varepsilon x \end{bmatrix} = -\varepsilon(x^2 + y^2)$.

When $x^2 + y^2 = 0$ then $(x, y) = (0, 0)$ and we find $R(0, 0) = (0, 0) \forall R \in O(2)$.

When $x^2 + y^2 \neq 0$ then $-\varepsilon(x^2 + y^2) = \mp(x^2 + y^2) \neq 0 \therefore$ for fixed ε

there exists a unique solⁿ to (*). Continued,

$$\boxed{\varepsilon = 1} \quad \begin{bmatrix} x & y \\ y & -x \end{bmatrix} \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} \quad \text{for } (x, y) \neq (0, 0)$$

$$\Rightarrow \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \frac{1}{-x^2 - y^2} \begin{bmatrix} -x & -y \\ -y & x \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{x^2 + y^2} \begin{bmatrix} x^2 + y^2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\text{So } \cos \theta = 1 \quad \text{and } \sin \theta = 0 \quad \therefore \underline{\theta = 0}.$$

$$\therefore \underline{R = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}.$$

$$\boxed{\varepsilon = -1} \quad \begin{bmatrix} x & y \\ -y & x \end{bmatrix} \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} \quad \text{for } (x, y) \neq (0, 0)$$

$$\Rightarrow \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = \frac{1}{x^2 + y^2} \begin{bmatrix} x & -y \\ y & x \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{x^2 + y^2} \begin{bmatrix} x^2 - y^2 \\ 2xy \end{bmatrix}$$

$$\therefore \cos \theta = \frac{x^2 - y^2}{x^2 + y^2} \quad \text{and} \quad \sin \theta = \frac{2xy}{x^2 + y^2}$$

$$R_v = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix} = \frac{1}{x^2 + y^2} \begin{bmatrix} x^2 - y^2 & 2xy \\ 2xy & y^2 - x^2 \end{bmatrix}$$

$$\text{Observe, } R_v \begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{x^2 + y^2} \begin{bmatrix} x(x^2 - y^2) + 2xy^2 \\ 2x^2y + y(y^2 - x^2) \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix}.$$

$$\text{Thus, } \boxed{G_v = \{ I, R_v \} \quad \text{for } v = (x, y) \neq (0, 0)}$$

P70 Gallian # 27 from pg. 146

Let H, K be subgroups of a finite group G
and $H \leq K \leq G$. Prove $[G:H] = [G:K][K:H]$

By Lagrange's Th^m, $[G:K] = \# \text{ of } K\text{-cosets in } G = \frac{|G|}{|K|}$

likewise, $[K:H] = \# \text{ of } H\text{-cosets in } K = \frac{|K|}{|H|}$

and $[G:H] = \frac{|G|}{|H|} = \frac{|G|}{|K|} \cdot \frac{|K|}{|H|} = [G:K][K:H]. //$

Remark: we needed finiteness of H, K, G to apply Lagrange Th^m.

P71 Find all homomorphisms from \mathbb{Z}_5 to \mathbb{Z}_7

Clearly $\phi: \mathbb{Z}_5 \rightarrow \mathbb{Z}_7$ defined by $\phi(x) = 0 \quad \forall x \in \mathbb{Z}_5$
defines a function with $\phi(x+y) = \phi(x) + \phi(y) \quad \forall x, y \in \mathbb{Z}_5$.
This ϕ is the trivial homomorphism.

Suppose $\psi: \mathbb{Z}_5 \rightarrow \mathbb{Z}_7$ is a nontrivial map.

Observe $0 = \psi(0) = \psi(5(1)) = \psi(1+1+1+1+1)$
 $= \psi(1) + \psi(1) + \psi(1) + \psi(1) + \psi(1)$
 $= 5\psi(1)$ } *

Hence, $5\psi(1) = 0$ in $\mathbb{Z}_7 \Rightarrow |\psi(1)| \mid 5 \Rightarrow |\psi(1)| = 1$ or 5 .

But, $\langle \psi(1) \rangle \leq \mathbb{Z}_7 \Rightarrow |\psi(1)| = 1$ or $|\psi(1)| = 7$ thus $|\psi(1)| = 1$

which implies $\psi(1) = 0$ and $\psi(x) = x\psi(1) = x(0) = 0$. Thus

ψ is the trivial homomorphism.

using * generalized
which we know from
previous studies...

This contradicts $\psi \neq \phi$. Thus,

$\phi \equiv 0$ is the only homomorphism from $\mathbb{Z}_5 \rightarrow \mathbb{Z}_7$.

P72 Let $\phi: \mathbb{Z}_n \rightarrow \mathbb{Z}_k$ be a homomorphism.

Consider, $\phi([1]_n) = [m]_k$ for some $m \in \mathbb{Z}$.

However, $\phi([0]_n) = \phi([n]_n) = 0 \Rightarrow 0 = \phi([n]_n) = n\phi([1]_n)$

or $n[m]_k = [nm]_k = 0$ thus $k \mid mn$. Moreover,

$$\begin{aligned}\phi([x]_n) &= \phi(x[1]_n) \\ &= x\phi([1]_n) \\ &= x[m]_k\end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \phi \text{ a homomorphism.}$$

$$= [mx]_k \quad \therefore \phi([x]_n) = [mx]_k \text{ for all } [x]_n \in \mathbb{Z}_n \text{ for some } m \text{ where } k \mid mn.$$

For example,

$\phi: \mathbb{Z}_6 \rightarrow \mathbb{Z}_4$ defined by

$\phi([x]_6) = [2x]_4$ defines homomorphism

since $2(6) = 12$ is multiple of 4.

Remark: this result informs how to search for all homomorphisms from $\mathbb{Z}_n \rightarrow \mathbb{Z}_k$ in terms of finding m for which $k \mid mn$.